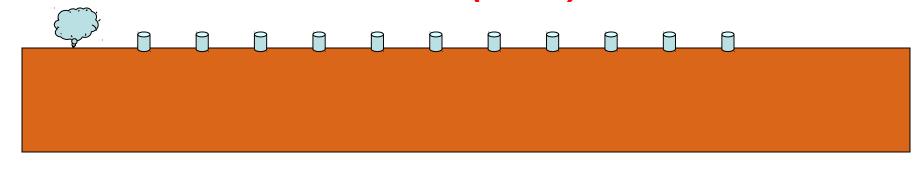
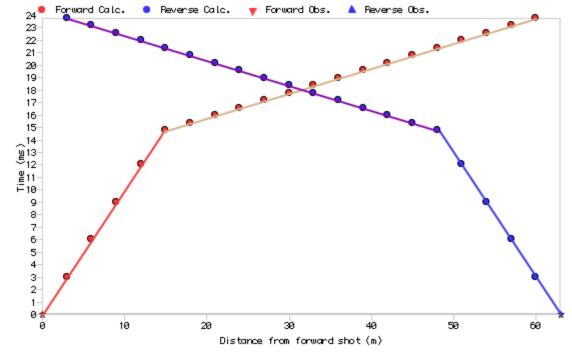
## The Refraction Method

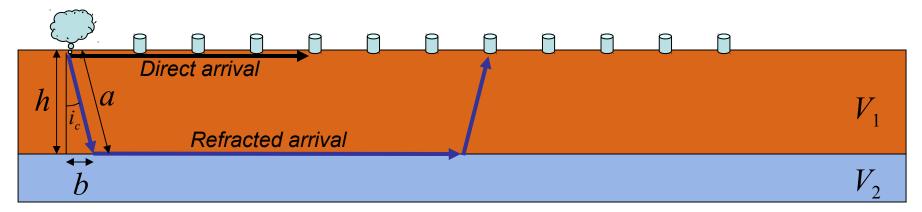
Recall first arriving seismic wave is the *direct wave* near the source, and *refracted (head) waves* further out:





## **Problem:**

We start knowing little or nothing about the subsurface, and our objective is to use the *observations* to learn what's under our feet.



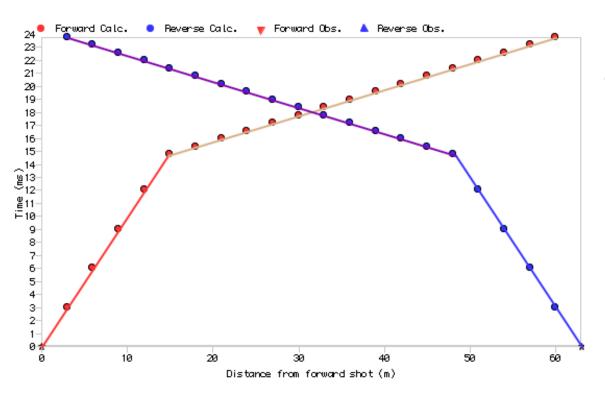
Consider the simple case of one horizontal layer over a half-space with higher velocity:

Direct wave travels horizontally at velocity  $V_1$ . On a plot of time vs. distance, arrivals are a straight line with **slope**  $\Delta t / \Delta x = 1/V_1$  and **intercept** t = 0, i.e.,  $t = x/V_1$ .

Refracted wave travels horizontally at velocity  $V_2$  at the top of layer 2, so a line with **slope**  $1/V_2$ . The **intercept** now adds the time traveled in the first layer (& subtracts the time not traveled in the second layer), i.e.,  $t_0 = 2a/V_1 - 2b/V_2$ . This wave has incident angle  $i_c = \sin^{-1}(V_1/V_2)$ , so

$$t = \frac{x}{V_2} + \frac{2a}{V_1} - \frac{2b}{V_2} = \frac{x}{V_2} + \frac{2h\sqrt{V_2^2 - V_1^2}}{V_1V_2}$$

(HW # 1-4)

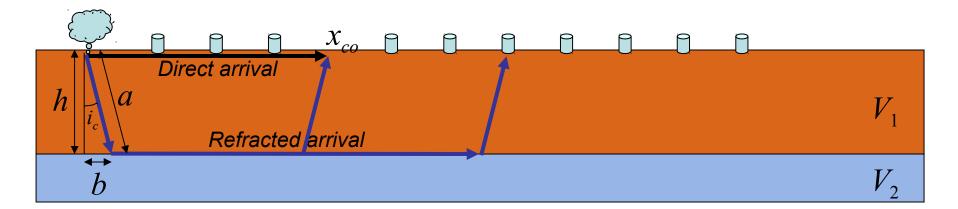


The mathematical simplicity of finding structure from slope & intercept of a line made refraction the tool of choice in early imaging studies!

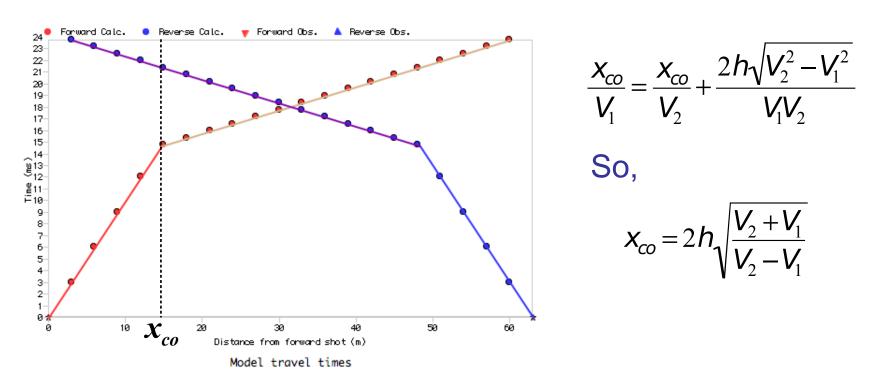
So, can fit lines  $t = m_i x + b_i$  to the first arrival travel-times... Then  $V_1 = 1/m_1$ ,  $V_2 = 1/m_2$ , and

$$h = \frac{b_2 V_1 V_2}{2\sqrt{V_2^2 - V_1^2}}$$

In the plot above,  $m_1 = 0.001$  s/m,  $m_2 = 0.0002$  s/m,  $b_2 = 0.0118$  s. What are the velocities & depth? (Exercise)

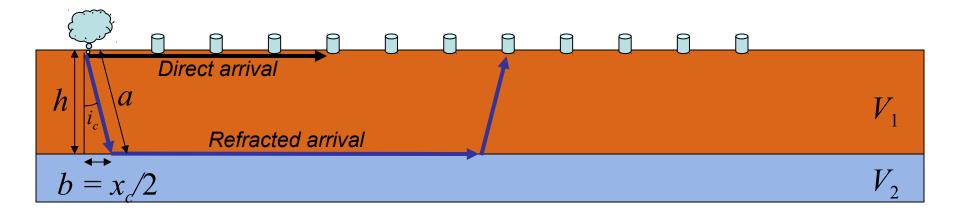


**Practical note:** The following works for a horizontal interface, and **then only** if there are enough geophones before & after the **crossover distance**  $x_{co}$  (where arrival times for the direct & refracted arrival are the same):



$$x_{co} = 2h\sqrt{\frac{V_2 + V_1}{V_2 - V_1}}$$

**Spatial sampling** is key to getting accurate estimates of thickness: Must have multiple geophones that sample each layer. Since we don't know the structure when designing the experiment, this means lots of closely-spaced geophones... Where "close" is determined by minimum expected thickness and maximum expected velocity difference!

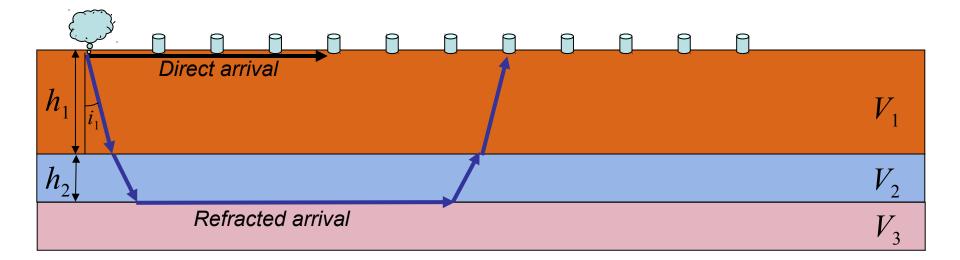


Another important term in refraction studies is the *critical distance*, the horizontal distance traveled in layer 1 by a ray at the *critical angle*,  $i_c$ :

$$x_c = 2b$$

$$\tan i_c = \frac{\frac{x_c}{2}}{h} \implies x_c = 2h \tan \left( \sin^{-1} \left( \frac{V_1}{V_2} \right) \right) = \frac{2hV_1}{\sqrt{V_2^2 - V_1^2}}$$

In situations where we have some approximate idea of the range of thicknesses & velocities we might expect to find, calculating the crossover and critical distances inform *experiment design* (i.e., how many geophones to use, offset & spacing).



## For *multiple layers* we take advantage of Snell's Law:

$$\frac{\sin i_1}{V_1} = \frac{\sin i_2}{V_2} = \frac{\sin i_3}{V_3} \implies \sin i_c = \frac{V_2}{V_3}; \sin i_1 = \frac{V_1}{V_3}$$

Via similar algebra & geometry to the one-layer case,

$$t = \frac{x}{V_3} + \frac{2h_1\sqrt{V_3^2 - V_1^2}}{V_3V_1} + \frac{2h_2\sqrt{V_3^2 - V_2^2}}{V_3V_2}$$

or, generalizing to *n*-layers:

$$t = \frac{x}{V_n} + \sum_{i=1}^{n-1} \frac{2h_i \sqrt{V_n^2 - V_i^2}}{V_n V_i}$$